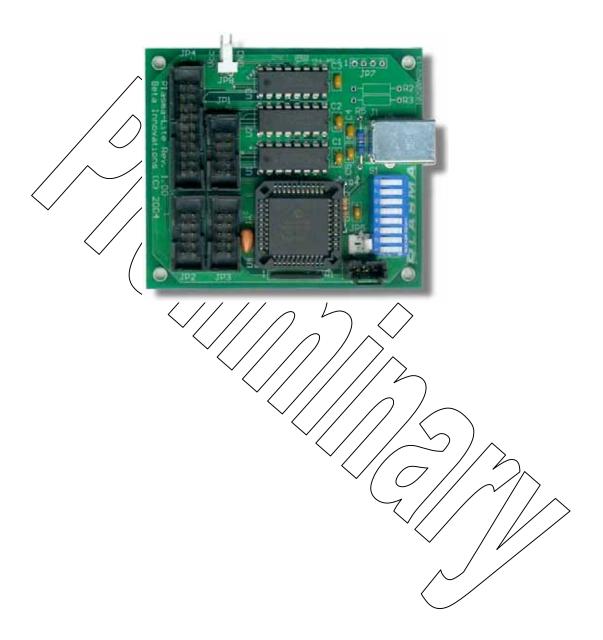
Plasma Lite USB Module

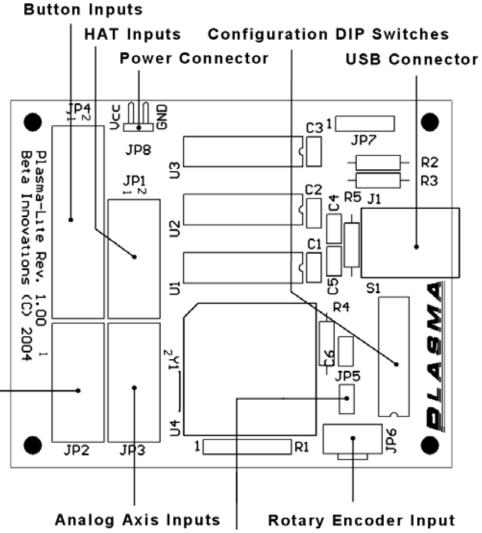


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Table of Contents

Main Features4
Introduction5
Plasma Configuration6
Configuration Selection DIP Switches6
Configuration Options .)6
Plasma-Lite Pin-Qut8
Digital POV HAT Inputs
Connecting Digital POV HATS8
Mechanical Rotary Encoder Input9
Connecting Rotary Encoders9
Button Inputs
Connecting Various Switches – All Modes 10
SPST Toggle Switches (On-Off)
SPDT Switches (On-On)
Rocker Switches (On-Off-On)
Push Button Switches
Rotary Switches
Mechanical / Optical Rotary Encoders12
Multi-Position Rotary Switches12
Analog Port Inputs
Connecting Potentiometers to Analog Inputs
Connecting Hall Effect Sensors to Analog Inputs
Connecting Linear Transducers to Analog Inputs
Connecting Analog Joystick Pots
Axis Synchronization15
Connecting Axis Synchronization Switch
Hardware Specifications16
Mechanical Specifications17
Rill Of Materials

Plasma Lite USB Module



ACE Board Connector Axis Sychronization Switch Input



Main Features

■ Easy installation

The Plasma Lite device is a Low Speed USB HID compliant device, which uses default drivers and powered by the USB Bus.

■ Analog Axis Input

Supports a variety of input devices including, Potentiometers, Hall Effect sensors, and pressure transducers or force sensors for precise control.

■ Digital Axis Input

Supports up to 4 ACE (Absolute Contacting Encoder) rotaries through a separate daughter board.

■ Filtering Algorithm

Features a proprietary selectable 2 level Recursive Moving Delta Sigma filtering algorithm virtually eliminating noise, spike and jitter for stable output.

■ Axis Resolutions

Selectable analog axis resolution from 32 to 256 steps (128 steps max for ACE rotaries).

■ POV HAT Support

2 Digital 8-way POV HAT inputs.

■ Button Inputs

16 button inputs (Active Low) compatible with any king of switch: toggle, push button, etc.

■ Trim Switch / Rapid Fire Inputs

2 rapid fire inputs producing 10 pulses per second which can be used for trim switch functions.

■ Buffered Rotary Encoder Support

Dedicated channel for a rotary encoder (2 bit gray code) Buffered outputs prevent lost inputs when rotary is turned rapidly.

■ Analog Axis Synchronization

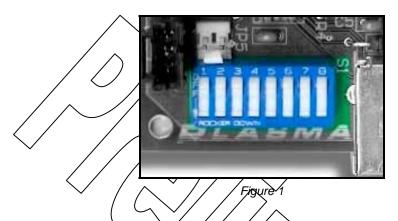
Up to 4 analog axis inputs can be synchronized to eliminate asymmetric thrust on multi-lever throttles due to linearity differences between potentiometers or any other input devices.

■ Mode of Operation

Adheres to Plasma's *SINGLE* device Mode A operational parameters. Enumerates as 8X16B1R2H (8 axis, 16 buttons, 1 rotary, 2 HATs) device in Plasma *SINGLE Mode* configuration.

Introduction

The Plasma Lite USB adapter is configurable through selection switches (Figure 1). In each case the Plasma unit will reconfigure itself without the need to re-enumerate as USB device. As such, the configuration settings can be altered at any time during normal operation without the need to disconnect the device form the USB bus.



Unlike the Plasma V2 module this device operates in a single mode of operation at all times and adheres to all Plasma functionality with respect to Mode A only.

Mode A: Plasma - USB Adaptor

Device 1 – 8 axis, 14 buttons, 2 Rapid Fire inputs, 1 Rotary Encoder and 2 POV HATS

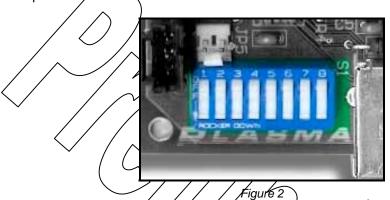
Note: This device does not support Modes B through C (Refer to Plasma User Manual for details on these Modes).

Plasma Configuration

The Plasma Lite module has several user adjustable DIP switches that allow the configuration of various onboard systems and device features.

Configuration Selection DIP Switches

Configuration selection DIP switches (Figure 2) can be used to activate additional operational features.



DIP Switch S1:

Switch 1 - Level 1 Analog Axis Filter

Switch 2 - Level 2 Analog Axis Filter, Level 1 must be active

Switch 3 - ACE Rotaries on X & Y Axis

Switch 4 – ACE Rotaries on Z & Rx Axis

Switch 5 - Axis Synchronization/

Switch 6 – 2 / 4 Axis Synchronization

Switch 7 - Analog Axis Resolution LSB (Least Significant Bit)

Switch 8 - Analog Axis Resolution M&B (Most Significant Bit)

Configuration Options

Level 1 Analog Axis Filter: is adequate for eliminating a substantial amount of jitter (noise), but has poor attenuation properties on spikes and extreme cases of line noise. This level of filtering has no noticeable effect on input sensitivity.

Level 2 Analog Axis Filter: virtually eliminates most forms of spiking and line noise but may adversely affect input sensitivity. As a result, level 2 filtering should only be activated when absolutely necessary. Level 2 filtering will only work in conjunction with level 1 filtering therefore level 1 filtering must be turned ON.

NOTE: ACE rotaries are not filtered due to their digital nature.

To activate filtering, toggle ON the appropriate dip switch on S1.

A substantial improvement was made over the filtering algorithm used in the previous version of Plasma with the addition of a user selectable level of filtering for jitter (noise) and spikes, the two most common drawbacks associated with potentiometers.

Beta Innovations

In certain instances where raw input data is preferred, reducing the axis resolution can be sufficient to effectively eliminate these undesired elements.

ACE Rotaries – If you have connected an ACE add-on board to your Plasma Lite unit you can activate the add-on module by toggling ON switch 3 and/or 4 on S1.

ACE Rotaries on X & Y Axis – Toggling ON switch 3 on S1, ACE rotary digital data will be used for the X & Y axis inputs. The X and Y analog axis ports on the device will no longer be active and ACE digital data will be used instead.

ACE Rotaries on Z & Rx Axis – Toggling ON switch 4 on S1, ACE rotary digital data will be used for the Z & Rx axis inputs. The Z and Rx analog axis ports on the device will no longer be active and ACE digital data will be used instead.

NOTE: ACE axis data cannot be diverted to any other analog axis ports and are ideally suited for throttle levers.

Axis Synchronization – The device is equipped with an analog axis synchronization feature. Switch 5 will activate this feature and can be toggled ON/OFF through a momentary push button switch connected to JP5.

2 / 4 Axis Synchronization — If switch 6 is set to OFF, only the X & Y axis on the device will be synchronized. When switch 6 is set to ON, X, Y, Z and Rx axis will be synchronized. Synchronization can be toggled ON/OFF through a momentary push button switch connected to JP5.

Analog Axis Resolution – All analog axes have 4 pre-settable axis resolutions. One setting affects all analog inputs on the Plasma unit. The step number represents the maximum number of possible discrete positions on the output.

DIP Switch S1:

Switch 7 – Analog Axis Resolution LSB

Switch 8 - Analog Axis Resolution MSB

32 step resolution:

Switch 7 – off

Switch 8 - off

64 step resolution:

Switch 7 – on

Switch 8 - off

128 step resolution:

Switch 7 - off

Switch 8 – on

256 step resolution:

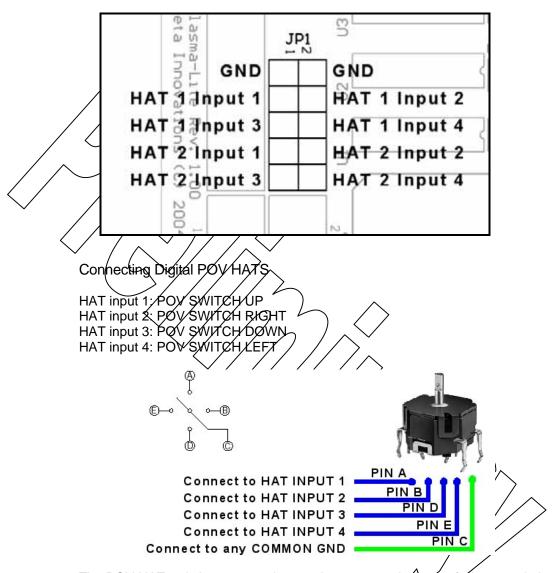
Switch 7 - on

Switch 8 - on

The higher the step size the more likely the output will suffer from the effects of jitter due to the LSB uncertainty in the ADC conversion process. As such, there is a trade off between resolution and stability of the output signal. The output signal stability is also heavily dependent on the use of high quality input devices (i.e Hall Sensors, Potentiometers, etc.). Therefore, activation of the digital filter is recommended if a clean stable signal is required at the output while maintaining a high degree of step size and resolution.

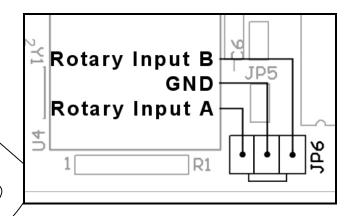
Plasma-Lite Pin-Out

Digital POV HAT Inputs

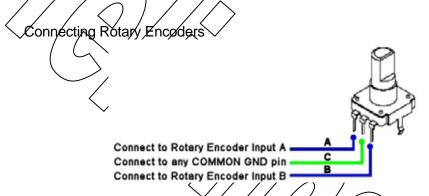


The POV HAT switch common pin must be connected to one of the ground pins. All other HAT switch pins must be connected to the appropriate input pins as describe above.

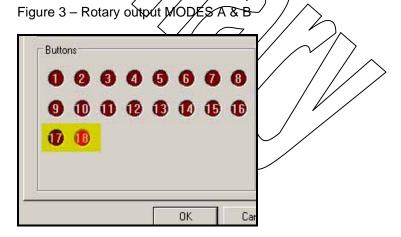
Mechanical Rotary Encoder Input



The mechanical fotary encoder inputs convert 2-bit gray code type encoders only that have the same number of detents and pulses. These inputs are buffered to prevent lost inputs with a maximum output rate limited to 12 PPS (Pulses Per Second). The pulse output is comprised of a 40 ms ON pulse followed by a 40 ms OFF pulse.

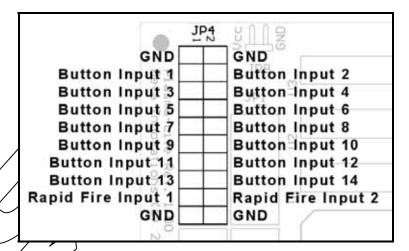


Rotary outputs are located on button inputs 17 & 18 illustrated below (Figure 3).



NOTE: Any software reading device inputs less than 25 Hz (25 times per second) will invariably drop inputs.

Button Inputs

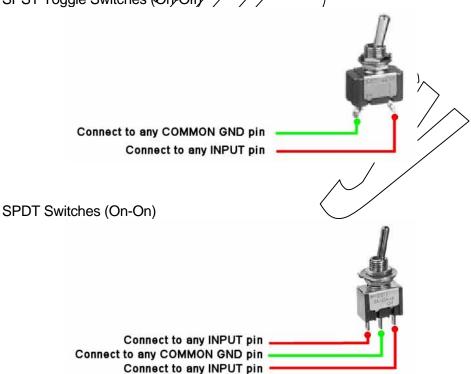


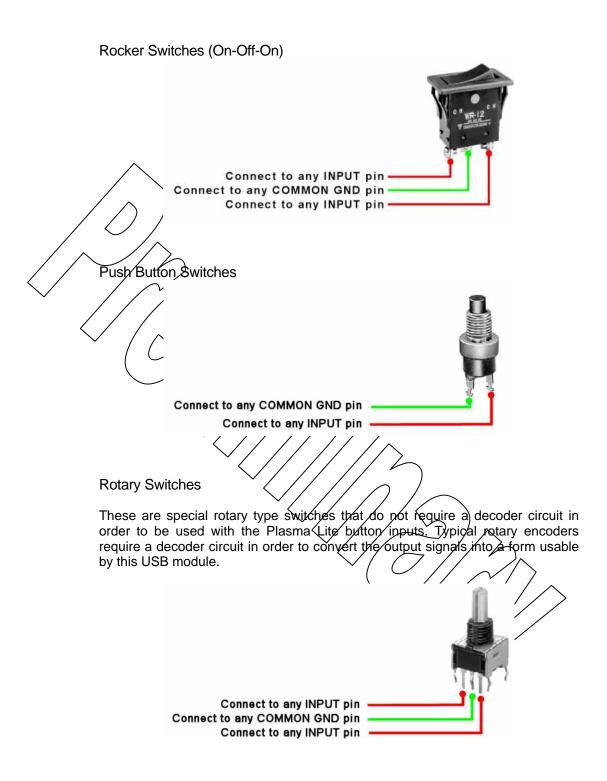
Unlike the standard button inputs, Rapid Fire Inputs send a pulse stream instead of a continuous ON signal. The pulse rate has been preset to 10 PPS (Pulses Per Second)

Connecting Various Switches All Modes

The Plasma module does not use a) scan matrix type of input layout. As such, diodes are not required and will not suffer from phantom signals when activating several switch inputs at the same time.

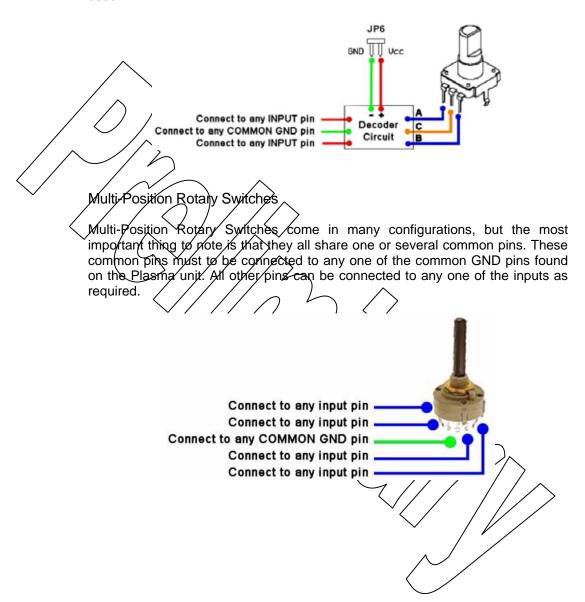
SPST Toggle Switches (On Off)



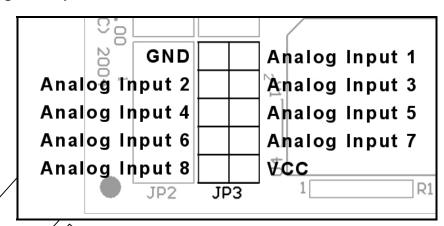


Mechanical / Optical Rotary Encoders

These types of rotary encoders require a decoder circuit in order to convert the output signals into a form usable by this USB module. Rotary output signals can be 2-bit gray code or 2-bit quadrature code depending on the decoder circuit used.



Analog Port Inputs



Analog Axis Inputs

Analog Input 1: X-Axis
Analog Input 2: Y-Axis

Analog Input 3:- Z-Axis Analog Input 4: X-Rotation

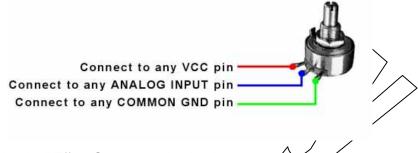
∕Analog Input 5: Y-Røtatio∕n

Analog Input 6: Z-Rotation

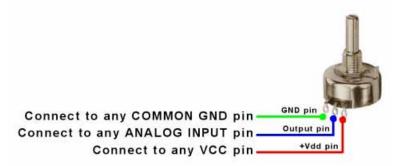
Analog Input 7: Slider 1/ Analog Input 8: Slider 2

NOTE: Some operating system's default USB drivers may not support 8 axis. MS Windows 98 (USB Upgrade) ME 2000/ XP support up to 8 axis per device.

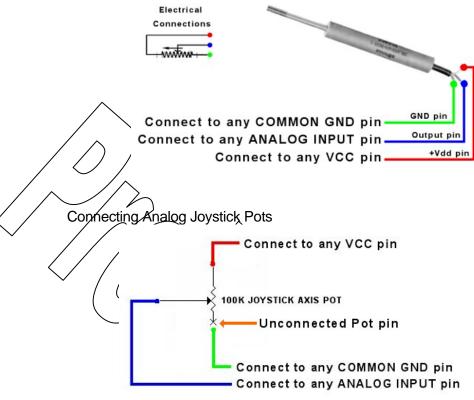
Connecting Potentiometers to Apalog Inputs



Connecting Hall Effect Sensors to Analog Inputs



Connecting Linear Transducers to Analog Inputs



NOTE: Conventional analog Joystick potentiometers have one unconnected pin on axis pots. It is imperative that this pin be grounded in order to properly function when connected to the Plasma analog port inputs.

Axis Synchronization

With the inherent linearity errors of potentiometers, analog input values can differ by as much as 20% under worst case conditions. This can cause undesired effects when precision between multiple analog input is required on 2 or 4 engine throttle quadrants.

Although more expensive solutions exist (i.e. ACE's, Hall Sensors, etc.) which do not suffer from these linearity differences, a simple solution is employed on select analog ports by averaging the inputs and eliminating these linear variations. This synchronization can be quickly activated when needed by pressing a momentary push button connected to JP5.

Connect to pin 1 JP5
Connect to pin 2 JP5

NOTE: Although axis synchronization can be used in conjunction with ACE rotaries, it should be noted that it is not required due to their high degree of linearity.

Hardware Specifications

The firmware runs at 40 ms iteration rate in operational Mode A. As such, any custom interface software should poll this device at least every 40 ms to prevent lost inputs. The 40 ms interval time is more than adequate to debounce switch contacts if any are used as inputs. Note that all inputs are active low, which means you must ground an input in order to register a high "ON" signal at the output.

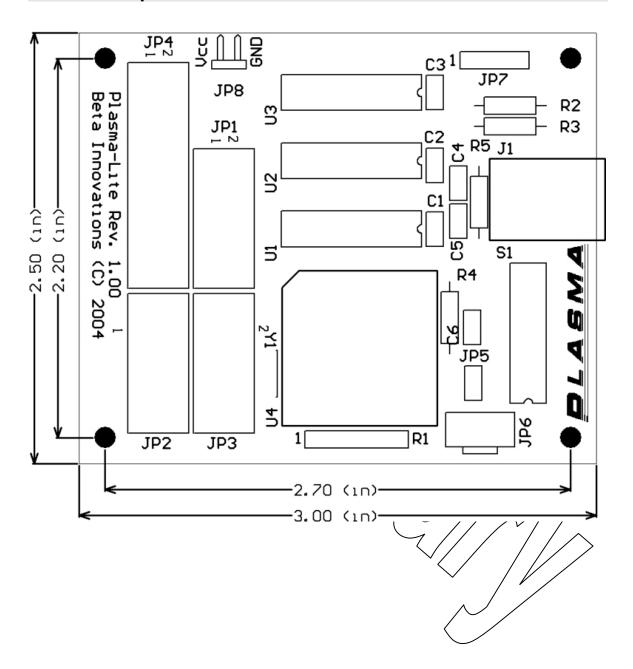
Most operating systems will detect and load the appropriate HID driver for your device and do not require that a custom device driver be installed. On some operating systems, these default drivers may not support all reatures of the Plasma Lite module.

Maximum power consumption is 500mW (100mA) and is powered by the USB bus. You do not need to use an external power supply for this device, even when connecting (and powering) several rotary decoder modules from the onboard power pins specifically added for this purpose.

NOTE: DO NOT CONNECT any of the Plasma Lite Vcc pins to external power supplies or voltage sources. Although common grounds can be safely connected to external grounds, it is not recommended and should be avoid whenever possible. Doing so may adversely affect performance, possibly causing strange or erraric behavior under certain conditions.



Mechanical Specifications



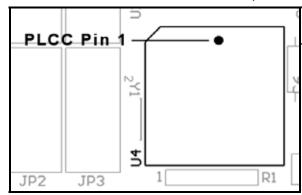
Bill Of Materials

```
C1
       0.1µF, 20%, 50VDC Ceramic
C2
       0.1µF, 20%, 50VDC Ceramic
C3
       0.1µF, 20%, 50VDC Ceramic
       0.1µF, 20%, 50VDC Ceramic
C4
       0.1µF, 20%, 50VDC Ceramic
C5
       0.1μF, 20%, 80VDC Ceramic
C6
       0.1µF, 20%, 50VDC Ceramic
C7
J1
       USB Type 'B' Connector
       Header, 10-Pin .100, Dual row
JP1
       Header, 10-Pin .100, Dual row
JP2
       Header, 10-Pip .100, Dual row
JP3
       Header, 20-Pin .100, Qual row
JP4
JP5
       Header, 2-Pin .100, Straight
JP6
       Connector receptacle, 3-Pin .100
       Header, 2-Pin .100, Right Angle
JP8
       EXB-F6E822G/8.2K, 10%, 1/4W, 5/Resistor pack with common pin
R1
       10K, 10%, 1/4W
R4
       1.5K, 1% Mertal Film, 1/4W/
R5
       AMP 435640-5 DIP Switch, & toggle switches
S1
       MC74HC4051AN-8-Channel Analog Multiplexer/Demultiplexer
U1
       MC74HC4051AN & Channel Apalog Multiplexer/Demultiplexer
U2
       MC74HC4051AN 8-Charnel Analog Multiplexer/Demultiplexer
U3
       PIC16C765-I/L EPROM-Based 8-Bit &MOS Microcontroller with A/D Converter
U4
       44 pin PLCC socket for U9
       6MHz Ceramic Resonator with integrated 22/pf capacitors
Y1
```

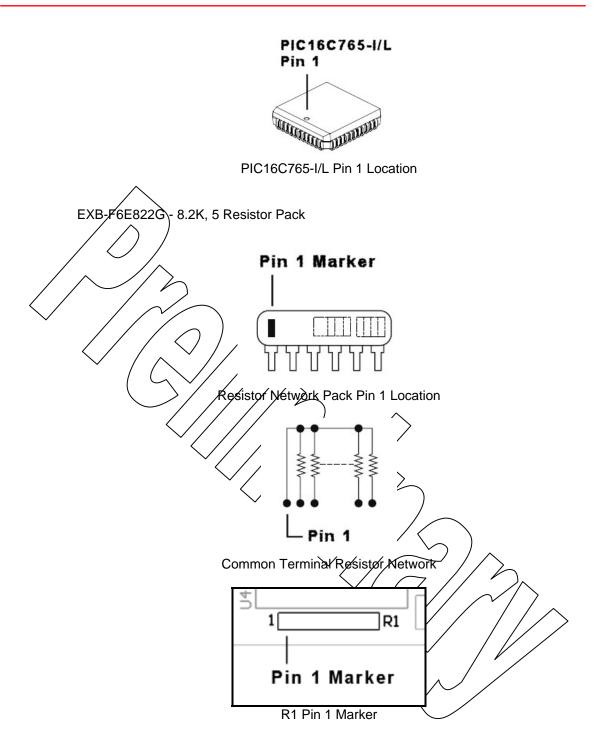
IMPORTANT: Care must be taken if substituting the analog multiplexer IC's (MC74HC4051AN) in order to minimize analog signal degradation and performance. If the MG74HC4051AN must be substituted, it is imperative that ICs with the lowest "on resistance" are selected.

Clearly identify all PIN 1 positions prior to component placement. Particular attention must be paid to the orientation of the following critical components:

PIC16C765-I/L Microcontroller



PLCC Socket Pin 1 Location



Visit www.betainnovations.com for the availability of kits, fully assembled modules and accessories.